

# Limit Theorems for Markov processes

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# Definitions

Let  $(X, \rho)$  be a Polish space. Let  $\mathcal{B}(X)$  be the space of all Borel subsets of  $X$  and let  $B_b(X)$  (resp.  $C_b(X)$ ) be the Banach space of all bounded, measurable (resp. continuous) functions on  $X$  equipped with the supremum norm  $\|\cdot\|_\infty$ . We denote by  $\text{Lip}_b(X)$  the space of all bounded Lipschitz continuous functions on  $X$ . By  $\mathcal{M}$  and  $\mathcal{M}_1$  we denote the family of Borel measures such that  $\mu(X) < \infty$  for  $\mu \in \mathcal{M}$  and  $\mu(X) = 1$  for  $\mu \in \mathcal{M}_1$ .

An operator  $P_* : \mathcal{M} \rightarrow \mathcal{M}$  will be called a *Markov operator* if it satisfies the following two conditions

- positive linearity:  $P_*(\lambda_1\mu_1 + \lambda_2\mu_2) = \lambda_1P_*\mu_1 + \lambda_2P_*\mu_2$  for  $\lambda_1, \lambda_2 \geq 0$ ;  $\mu_1, \mu_2 \in \mathcal{M}$ ;
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# Definitions

A Markov operator  $P_*$  is called a *Feller operator* if there is a linear operator  $P : C_b(X) \rightarrow C_b(X)$  such that

$$\int_X Pf(x)\mu(dx) = \int_X f(x)P_*\mu(dx)$$

for any  $f \in C_b(X)$  and  $\mu \in \mathcal{M}$ .

Let  $P_*$  be a Markov operator; a measure  $\mu \in \mathcal{M}$  is called *invariant* if  $P_*\mu = \mu$ . A Markov operator  $P$  is called *asymptotically stable* if there exists a stationary measure  $\mu_* \in \mathcal{M}_1$  such that

$$\text{w-lim}_{n \rightarrow \infty} P_*^n \mu = \mu_*$$

for any  $\mu \in \mathcal{M}_1$ .

# Invariant measures for Markov operators

Theorem 1. A. Lasota, J. Yorke (1994)

Let  $P_* : \mathcal{M} \rightarrow \mathcal{M}$  be a Feller operator. Assume that there is a compact set  $Y \subset X$  and a measure  $\mu_0 \in \mathcal{M}_1$  such that

$$\limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n P_*^k \mu_0(Y) > 0.$$

Then there exists an invariant measure  $\mu_* \in \mathcal{M}_1$ .



# Wasserstein metric

In the space  $\mathcal{M}$  we introduce the **Wasserstein distance**

$$d_w(\mu, \nu) = \sup \left\{ \left| \int_X f d(\mu - \nu) \right| : \|f\|_\infty \leq 1, \text{Lip } f \leq 1 \right\}$$

for  $\mu, \nu \in \mathcal{M}$ .

A Markov operator will be called *nonexpansive* if

$$d_w(P_*\mu, P_*\nu) \leq d_w(\mu, \nu) \quad \text{for } \mu, \nu \in \mathcal{M}_1.$$

# Stability of Markov operators

## Theorem 2. A. Lasota, J. Yorke (1994)

Let  $P_* : \mathcal{M} \rightarrow \mathcal{M}$  be a nonexpansive Markov operator. Assume that for every  $\varepsilon > 0$  there is a Borel set  $A$  with  $\text{diam } A \leq \varepsilon$  and a number  $\alpha > 0$  such that

$$\liminf_{n \rightarrow \infty} P_*^n \mu(A) \geq \alpha \quad \text{for } \mu \in \mathcal{M}_1.$$

Then  $P_*$  is asymptotically stable.

# Markov semigroups

Let  $((Z(t))_{t \geq 0})$  be a Markov process taking values in  $X$  and let  $(P^t)_{t \geq 0}$  be its transition semigroup.

We shall assume that the semigroup  $(P^t)_{t \geq 0}$  is *Feller*, i.e.  $P^t(C_b(X)) \subset C_b(X)$  and that the Markov family is *stochastically continuous*, which implies that:  
 $\lim_{t \rightarrow 0^+} P_t \psi(x) = \psi(x)$  for all  $x \in X$  and  $\psi \in C_b(X)$ .

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The semigroup  $(P^t)_{t \geq 0}$  has the e-property if the above condition holds at any  $x \in X$ .

Let  $(P_*^t)_{t \geq 0}$  be the dual semigroup defined on the space  $\mathcal{M}_1$  given by the formula

$$P_*^t \mu(B) := \int_X P^t \mathbf{1}_B d\mu \quad \text{for } B \in \mathcal{B}(X).$$

Recall that  $\mu_* \in \mathcal{M}_1$  is *invariant* for the semigroup  $(P^t)_{t \geq 0}$  (or the Markov family  $(Z(t))_{t \geq 0}$ ) if  $P_*^t \mu_* = \mu_*$  for all  $t \geq 0$ .

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# The set $\mathcal{T}$

For a given  $T > 0$  and  $\mu \in \mathcal{M}_1$  define

$$Q^T \mu := T^{-1} \int_0^T P_*^s \mu ds.$$

We write  $Q^T(x)$  in the particular case when  $\mu = \delta_x$ .

The crucial role is played by the set

$$\mathcal{T} := \{x \in X : \text{the family of measures } (Q^t(x))_{t \geq 0} \text{ is tight}\}.$$

- if  $\mathcal{T} \neq \emptyset$ , then the semigroup  $(P^t)_{t \geq 0}$  admits an invariant measure;
- if  $\mu_*$  is an invariant measure, then  $\text{supp } \mu_* \subset \mathcal{T}$ ;
- if  $x \in \mathcal{T}$ , then the sequence  $(Q^t(x))_{t \geq 0}$  weakly converges to some invariant measure.

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# Invariant measures for Markov semigroups

Theorem 3. (A. Lasota and T.S. (2006))

Let  $(P^t)_{t \geq 0}$  be a Feller semigroup. Assume that there exists a point  $z \in X$  such that for every  $\delta > 0$

$$\limsup_{T \rightarrow \infty} Q^T(x, B(z, \delta)) > 0 \quad \text{for some } x \in X.$$

If the semigroup  $(P^t)_{t \geq 0}$  has the e-property in  $z \in X$ , then  $z \in \mathcal{T}$ . Consequently,  $(P^t)_{t \geq 0}$  admits an invariant measure.

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# Uniqueness of an invariant measure for Markov semigroups

Theorem 4. (T. Komorowski, S. Peszat and T.S.(2010))

Assume that  $(P^t)_{t \geq 0}$  has the e-property and that there exists a point  $z \in X$  such that for every  $\delta > 0$  and every  $x \in X$

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Then  $(P^t)_{t \geq 0}$  admits a unique invariant measure  $\mu_*$ . Moreover,

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# Ergodic measures

An invariant measure  $\mu \in \mathcal{M}_1$  is called **ergodic** if every  $A \in \mathcal{B}(X)$  such that  $P_t \mathbf{1}_A = \mathbf{1}_A$  for  $t \geq 0$  satisfies  $\mu(A) \in \{0, 1\}$ .

We shall assume the following concentrating condition:  
(C) There exists a compact set  $K \subset X$  such that for any  $\varepsilon > 0$  and every  $x \in X$

$$\limsup_{T \rightarrow +\infty} Q^T(x, K^\varepsilon) > 0,$$

where  $K^\varepsilon = \{x \in X : \inf_{y \in K} \rho(x, y) < \varepsilon\}$ .

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If  $(P^t)_{t \geq 0}$  satisfies the e-property and  $x \in \mathcal{T}$ , then by  $\nu^x$  we denote the weak limit of  $(Q^t(x))_{t \geq 0}$ .

We may formulate the following result.

Theorem 5. (D. Worm and T.S. (2012))

If  $(P^t)_{t \geq 0}$  satisfies the e-property and  $(\mathcal{C})$ , then there exists a Borel set  $K_0 \subset K \cap \mathcal{T}$  such that

- $x \in \text{supp } \nu^x$  and  $\nu^x$  is ergodic for all  $x \in K_0$ ,
- if  $x, y \in K_0$  with  $x \neq y$ , then  $\nu^x \neq \nu^y$ ,
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We may formulate the following result.

## Theorem 5. (D. Worm and T.S. (2012))

If  $(P^t)_{t \geq 0}$  satisfies the e-property and  $(\mathcal{C})$ , then there exists a Borel set  $K_0 \subset K \cap \mathcal{T}$  such that

- $x \in \text{supp } \nu^x$  and  $\nu^x$  is ergodic for all  $x \in K_0$ ,
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Now we fix  $x_0 \in X$ . For  $f : X \rightarrow \mathbb{R}$  and  $\theta > 0$  we define the local Lipschitz constant

$$|f|_{Lip,\theta} := \sup \left\{ \frac{|f(x) - f(y)|}{\rho(x,y)} : x \neq y; x, y \in B(x_0, \theta) \right\}.$$

Proposition 6. (D. Worm and T.S. (2012))

Let  $(P^t)_{t \geq 0}$  satisfy the e-property and (C). If there are sequences  $t_n > 0$  and  $\delta_n \downarrow 0$  and a non-decreasing function  $C : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ , such that for all bounded and Lipschitz functions and  $\theta > 0$

$$|P^{t_n} f|_{Lip,\theta} \leq C(\theta)(\|f\|_\infty + \delta_n \text{Lip } f).$$

Then  $(P^t)_{t \geq 0}$  admits only finitely many ergodic measures.

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# Application to Stochastic Equations

We study the Markov process defined by the stochastic evolution equation

$$dZ(t) = (AZ(t) + F(Z(t))) dt + R dW(t). \quad (1)$$

- $A$  is the generator of a  $C_0$ -semigroup  $S = (S(t))_{t \geq 0}$  on some real separable Hilbert space  $\mathcal{X}$ ,
- $F$  maps (not necessarily continuously)  $D(F) \subset \mathcal{X}$  into  $\mathcal{X}$ ,
- $R$  is a bounded linear operator from another Hilbert space  $\mathcal{H}$  to  $\mathcal{X}$ , and
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# Application to Stochastic Equations

We suppose that for every  $x \in \mathcal{X}$  there is a unique mild solution  $Z^x = (Z_t^x)_{t \geq 0}$  of (1) starting at  $x$ , and that (1) defines in that way a Markov family. We assume that for any  $x \in \mathcal{X}$ , the process  $Z^x$  is stochastically continuous.

The corresponding transition semigroup is given by

$$P_t \psi(x) = \mathbb{E} \psi(Z^x(t)),$$

$\psi \in B_b(\mathcal{X})$ , and we assume that it is Feller.

A function  $\Phi: \mathcal{X} \mapsto [0, +\infty)$  will be called a **Lyapunov function**, if it is measurable and

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# Applications to SPDE's

We shall assume that the deterministic equation

$$\frac{dY(t)}{dt} = AY(t) + F(Y(t)), \quad Y(0) = x \quad (2)$$

defines a continuous semi-dynamical system

$$Y^x = (Y^x(t), t \geq 0).$$

A set  $\mathcal{K} \subset \mathcal{X}$  is called a **global attractor** for  $Y^x$  if

- 1) it is invariant under the semi-dynamical system, i.e.  
 $Y^x(t) \in \mathcal{K}$  for any  $x \in \mathcal{K}$  and  $t \geq 0$ .
- 2) for any  $\varepsilon, R > 0$  there exists  $T$  such that  
 $Y^x(t) \in \mathcal{K} + \varepsilon B(0, 1)$  for  $t \geq T$  and  $\|x\|_{\mathcal{X}} \leq R$ .



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# Applications to SPDE's

The family  $(Z^x(t))_{t \geq 0}$ ,  $x \in \mathcal{X}$ , is **stochastically stable** if for every  $\varepsilon$ ,  $R$ ,  $t > 0$

$$\inf_{x \in B(0,R)} \mathbb{P}(\|Z^x(t) - Y^x(t)\|_{\mathcal{X}} < \varepsilon) > 0.$$

# Applications to SPDE's

## Theorem 5. (T. K., S. P. and T.S. (2010))

Assume that:

- there exists a global attractor  $\mathcal{K}$  of the semi-dynamical system  $(Y^x(t), t \geq 0)$  defined by (2);
- there exists a certain Lyapunov function  $\Phi$  such that

$$\sup_{t \geq 0} \mathbb{E} \Phi(Z^x(t)) < \infty \quad \text{for any } x \in \mathcal{X},$$

- the family  $(Z^x(t))_{t \geq 0}$ ,  $x \in \mathcal{X}$ , is stochastically stable, its transition semigroup has the e-property and

$$\bigcap_{x \in \mathcal{K}} \bigcup_{t \geq 0} \Gamma^t(x) \neq \emptyset, \quad (3)$$

where  $\Gamma^t(x) = \text{supp } P_t^* \delta_x$

## Theorem 5. (continuation)

Then,  $(Z^x(t))_{t \geq 0}$ ,  $x \in \mathcal{X}$  admits a unique invariant measure  $\mu_*$ . Moreover, we have

$$\text{w-lim}_{t \rightarrow \infty} Q^t \mu = \mu_*$$

for any  $\mu \in \mathcal{M}_1$ .

If we additionally assume that the attractor  $\mathcal{K}$  is a singleton, then  $(P^t)_{t \geq 0}$  is asymptotically stable, i.e.

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# The CLT and LIL

If we assume additionally that the Markov semigroup  $(P_t)_{t \geq 0}$  corresponding to some Markov process  $(Z(t))_{t \geq 0}$  is exponentially convergent, i.e., there exists  $\alpha > 0$  such that for any Lipschitz function  $f$  and  $x \in X$  there exists a constant  $C := C(f, x) > 0$  such that

$$|P_t f(x) - \int_X f d\mu_*| \leq C e^{-\alpha t},$$

where  $\mu_*$  is a unique invariant measure for the given semigroup, then for any bounded Lipschitz function  $\varphi : X \rightarrow \mathbb{R}$  such that  $\int_X \varphi d\mu_* = 0$  we obtain:

# The CLT and LIL

**The Central Limit Theorem:** For  $W_x(t) = \int_0^t \varphi(Z^x(s)) ds$  we have

$$\frac{W_x(t)}{\sqrt{t}} \implies W, \quad \text{as } t \rightarrow +\infty,$$

where  $W$  is a random variable with normal distribution  $\mathcal{N}(0, D)$  and the convergence is understood in law.

**The Law of the Iterated Logarithm:**

$$\limsup_{t \rightarrow +\infty} \frac{W_x(t)}{\sqrt{2t \log \log t}} = D$$

with probability 1. Of course the above implies that also

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# Model of passive tracer

Consider the Navier–Stokes equations (N.S.E.) on a two dimensional torus  $\mathbb{T}$ ,

$$\begin{aligned}\partial_t \vec{u}(t, x) + \vec{u}(t, x) \cdot \nabla_x \vec{u}(t, x) &= \Delta_x \vec{u}(t, x) - \nabla_x p(t, x) + \vec{F}(t, x), \\ \nabla \cdot \vec{u}(t, x) &= 0, \\ \vec{u}(0, x) &= \vec{u}_0(x).\end{aligned}\tag{4}$$

The two dimensional vector field  $\vec{u}(t, x)$  and scalar field  $p(t, x)$  over  $[0, +\infty) \times \mathbb{T}$ , are called an Eulerian velocity and pressure, respectively. The forcing  $\vec{F}(t, x)$  is assumed to be a Gaussian white noise in  $t$ , homogeneous and sufficiently regular in  $x$  defined over a certain probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

# Model of passive tracer

The trajectory of a tracer particle is defined as the solution of the ordinary differential equation (o.d.e.)

$$\frac{dx(t)}{dt} = \vec{u}(t, x(t)), \quad x(0) = x_0, \quad (5)$$

where  $x_0 \in \mathbb{R}^2$ .

Thanks to well known regularity properties of solutions of N.S.E  $\vec{u}(t, x)$  possesses continuous modification in  $x$  for any  $t > 0$ . However, since  $\vec{u}(t, x)$  needs not be Lipschitz in  $x$ , the equation might not define  $x(t)$ ,  $t \geq 0$ , as a stochastic process over  $(\Omega, \mathcal{F}, \mathbb{P})$ , due to possible non-uniqueness of solutions.

# Model of passive tracer

Let  $x_0 \in \mathbb{R}^2$ . By a *solution to (5)* we mean any  $(\mathcal{F}_t)$ -adapted process  $x(t)$ ,  $t \geq 0$ , with continuous trajectories, such that

$$x(t) = x_0 + \int_0^t \vec{u}(s, x(s)) ds, \quad \forall t \geq 0, \quad \mathbb{P}\text{-a.s.} \quad (6)$$

In our approach a crucial role is played by the *Lagrangian process*

$$\vec{\eta}(t, x) := \vec{u}(t, x(t) + x), \quad t \geq 0, \quad x \in \mathbb{T}$$

that describes the environment from the vantage point of the moving particle. It turns out that its rotation in  $x$ ,

$$\omega(t, x) = \text{rot } \vec{\eta}(t, x) := \partial_2 \eta_1(t, x) - \partial_1 \eta_2(t, x), \quad t \geq 0, \quad x \in \mathbb{T},$$

satisfies a stochastic partial differential equation (s.p.d.e.) that is similar to the stochastic N.S.E.

# Model of passive tracer

The position  $x(t)$  of the particle at time  $t$ , can be represented as an additive functional of the Lagrangian process, i.e.

$$x(t) = \int_0^t \psi_*(\omega(s)) ds,$$

We proved that the process under consideration satisfies the **CLT** (joint paper with T. Komorowski and S. Peszat, (2013)). Recently we have shown that the **LIL** holds also (with T. Komorowski, to appear in J. London Math. Soc.)